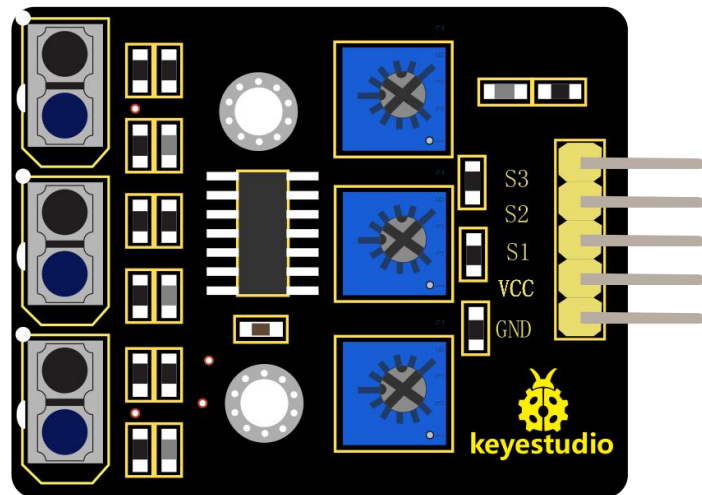




Keyestudio 3-channel Line Tracking Module (Black and Eco-friendly)



Description

In the smart car DIY process, we often use a line tracking sensor to make the smart car follow a line.

The keyestudio 3-channel line tracking module actually is an infrared sensor. The component used is a TCRT5000 infrared tube.

The working principle is to use the different reflectivity of infrared light to color, converting the strength of the reflected signal into a current signal.

During the detection, black is active at HIGH level, and white is active at LOW.

The detection height is 0-3 cm.



We have integrated three groups of TCRT5000 infrared tubes on a single board, convenient for wiring and control.

Turn the adjustable trimpot to adjust the module's sensitivity.

The module comes with two 3mm positioning holes for mounting on other devices.

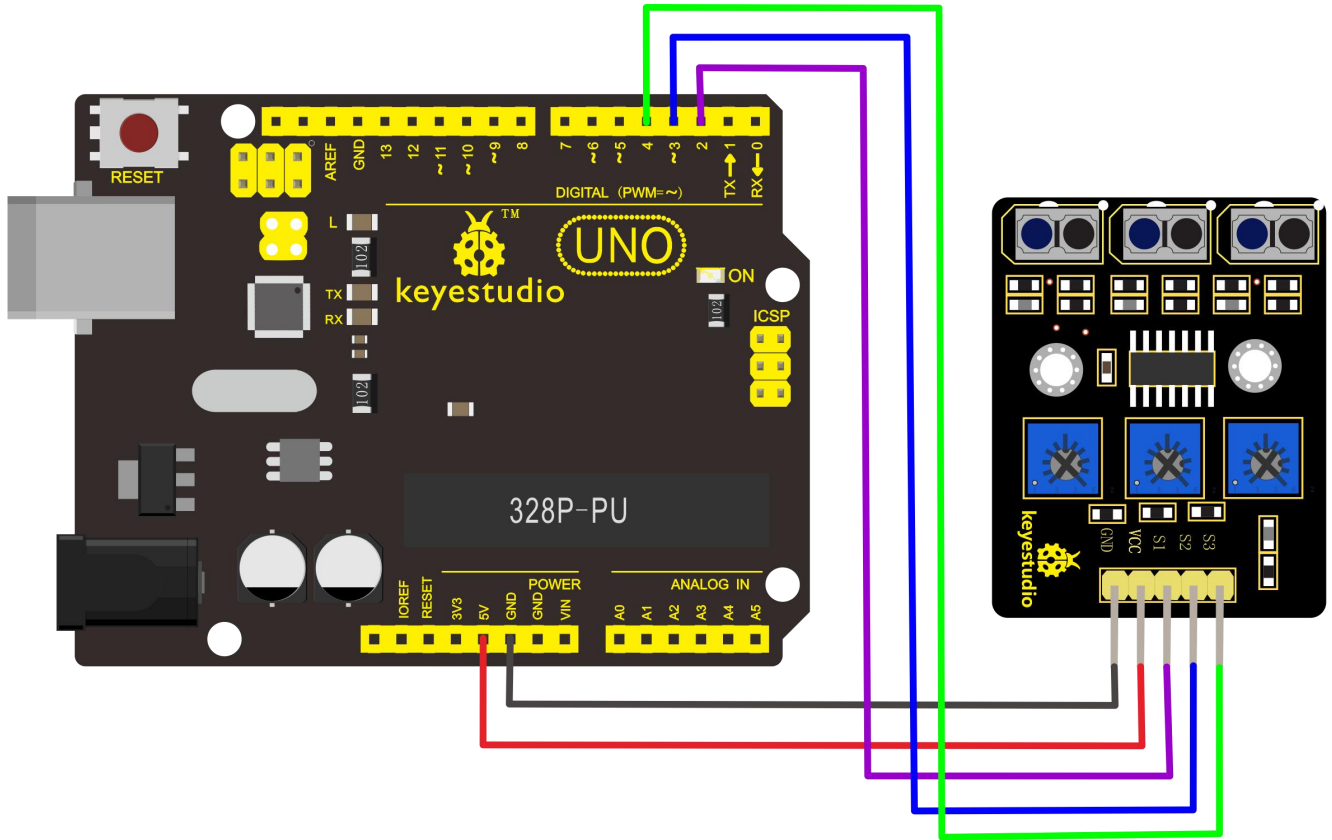
Note: before testing, turn the potentiometer to adjust the sensitivity. The sensitivity is the best when make the LED at the threshold point between ON and OFF.

Technical Parameters

- Operating voltage: DC 3.3-5V
- Detection height: 0—3cm
- Interface: 5pin of 2.54mm pitch
- Positioning hole diameter: 3mm
- Dimensions: 42mm*31mm*7mm
- Weight: 6.6g
- Environment attribute: ROHS



Wiring Diagram



Test Code

```
int sensor1 = 2;
```

```
int sensor2 = 3;
```

```
int sensor3 = 4;
```

```
int val1;
```

```
int val2;
```

```
int val3;
```

```
void setup()
```

```
{
```



```
Serial.begin(9600);  
  
pinMode(sensor1, INPUT); // set sensor to input mode  
pinMode(sensor2, INPUT); // set sensor to input mode  
pinMode(sensor2, INPUT); // set sensor to input mode  
  
}
```

```
void loop()  
{  
  val1=digitalRead(sensor1);  
  Serial.print("val1:");  
  Serial.print(val1);  
  val2=digitalRead(sensor2);  
  Serial.print("  val2:");  
  Serial.print(val2);  
  val3=digitalRead(sensor3);  
  Serial.print("  val3:");  
  Serial.println(val3);  
  delay(200);  
}
```

Test Result



Done uploading the code to control board, open the serial monitor and set the baud rate to 9600.

When the tacking module detects black line, output 1; detecting white line, output 0. As figure shown below.

